# **SAE Aero Micro**

# **Final Proposal**

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**Faculty Advisor: David Willy**

# **DISCLAIMER**

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# **EXECUTIVE SUMMARY**

The Northern Arizona University Aero Micro team was created to participate in the SAE Aero Micro Design competition. The function of the team is to create a remote-controlled airplane that meets the design requirements of the competition. However, the main goal of the team itself is to create a remotecontrolled airplane that can take-off and land safely. Customer Requirements (CR) and Engineering Requirements (ER) were taken from the competition rules and meetings with the client. From these CR's and ER's a House of Quality (Appendix A) was created to analyze the connections between them; they were then ranked to show which were most important to the project. It was then determined how to properly measure them and present the results. Which would be tested at a later date. After these steps the team created a Black Box Model and Functional Decomposition that broke down the main functions of the craft into 10 subsystems that could be further analyzed. From these 10 subsystems 30 different subsystem concept variants were made, all of which were combined into three final concept variants. From these three designs a final hybrid design was created.

The team began to analyze the hybrid design to see if it would be able to meet the requirements of the competition. After analytically analyzing the design, using volume, forces acting on the plane, overall weight, and the wingspan capabilities; it was discovered that while the design worked on paper, it couldn't be made to work in reality. The team began to create several iterations to find a design that would work analytically. Figure 1 is the final design the team was able to come up with. There is still a possibility that the design will change as the team progresses in the project, but for the present time, Figure 1 is the chosen design.

Leading into next semester, the team plans to fully build and test this design. The general analysis of this design, its validity and later tests are contained in the report below.



Figure 1: Final design

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# **1 BACKGROUND**

# *1.1 Introduction*

The SAE Aero Micro team was created as part of the SAE Aero international design competition. The design competition uses real world problems and constraints to challenge design teams to create a remotecontrolled airplane. For this specific project the team is participating in the SAE Aero Micro class competition. The Micro portion of the competition limits the teams to create a micro airplane through dimension and weight restrictions. The focus of this team, however, is to create an aircraft that can take off and land safely. This project is particularly important, as it showcases real world design constraints and expectations in a small-scale competition. This not only challenges the teams to create unique and functional designs, but it also showcases the nuances of conceptual design in the real world.

# *1.2 Project Description*

While the description of the project and the corresponding restraints were stated in the SAE Aero design competition rules and regulations, the main focus of this team is to create an aircraft that is able to takeoff and land safely. This is done over the period of one academic school year. This time frame includes concept creation, evaluation, prototyping and final testing. This project was created to not only test the team and individual teammates' understanding of engineering, but also to promote real-world thinking and teamwork through real-world problems. The sponsors for this project are Northern Arizona Universities Department of Mechanical Engineering, W.L. Gore. and the SAE Aero design competition committee. These project clients are Dr. David Willy of Northern Arizona University, and the SAE Aero design competition committee. With advice for the team by Dr. Willy.

# **2 REQUIREMENTS**

Section 2 showcases Customer requirements and the corresponding engineering requirements. Each of the requirements are listed and explained how they not only correspond with each other, but also how they are measured, weighted, and met through the final design. It is all combined in a visual aid called the House of Quality or the QFD.

# *2.1 Customer Requirements (CRs)*

For this project the Customer requirements were taken from the SAE Aero Design Competition rules, with clarification from the team's academic advisor, Dr. Willy. The customer requirements were then weighed on how important they are to the final design and how the final design should be constructed; on a percentage scale of 1-10. One being the least important, but still needed, and 10 being critical to the design. All the weights add up to 100%.

- 1. Meets the requirements of the [SAE] rules (8%)
- 2. Safe design (5%)
- 3. Abel to take off and land (8%)
- 4. Innovative design (3%)
- 5. Manufacturable (3%)
- 6. Low cost (3%)
- 7. Modular compatibility (1%)
- 8. Static load capability (5%)
- 9. 60 second lift-off time limit (4%)
- 10.200 feet landing distance (4%)
- 11.Payload extraction in 60 seconds or less (4%)
- 12.Use of lithium polymer batteries (4%)
- 13.Use of a 450-watt power limiter (4%)
- 14.Must have a cargo bay (4%)
- 15.Ability to make a turn in air (4%)
- 16.Ability to make a turn on the ground (4%)
- 17.Steering mechanism for landing gear (4%)
- 18.Must use an electric motor (4%)

19.Fixed wing (4%)

- 20.Functional failsafe for radio control systems (4%)
- 21.Must be equipped with a red arming plug (4%)
- 22.Must use model airplane safety nut (4%)
- 23.Appropriate center of gravity (4%)
- 24.Must have a radio control system (4%)

## *2.2 Engineering Requirements (ERs)*

The Engineering Requirements for the project were found through the Customer Requirements from the SAE Aero Design competition rules. The CR's were analyzed, and measurable parameters were created from them. These measurable parameters give solid data for the team to follow and attempt to meet. Table 1 shows the ERs, their set parameters, tolerances, the target numbers, the relative and absolute importance of each requirement and justifications for said parameters.





# *2.3 Functional Decomposition*

A Functional Decomposition is a breakdown of all the systems within a device and how they relate to one another. This also breaks down the overall systems into subsystems which can help the team members create accurate and detailed concepts that are able to meet the requirements of each subfunction. Figure 2 showcases the team's updated Functional Decomposition.



Figure 2: Functional Decomposition

The team was able to break down the aircraft into three main categories, with ten subsystems. The three main systems were the take-off, land, and cargo storage portion (blue portion). Take-off and landing are the main function of the aircraft, while the cargo storage is one of the main requirements of the competition. These systems were broken down into the ten subsystems (yellow, green), propeller, wings, motor, tail, landing gear, structure, aileron, servo, elevator, and cargo bay. Leading onto the designs, three different concept variants were made for each subsystem, and they were combined into three final complete designs. These designs were analyzed to ensure that each ER and CR would be met through the chosen design. The testing that occurred to showcase the validity of the design are outlined in Section 3.

Due to what the team has learned from analyzing the subsystems, three main things have changed within the design. These changes or realizations are boxed in purple. The first change made was to the structure, fuselage, and the resulting cargo hold. The fuselage and cargo hold were shortened, while two extending rods were added at the back for stability and weight reduction. Therefor the structure portion was changed into one of the main subsystems. The second change was made to the wings. Larger wings were needed in the front and back of the plane to ensure that the plane would be able to take-off and land. The third main change was the realization that the wings and tail will need reinforced interior structures to not only withstand general flight, but it also mitigates the potential damage caused by crash landing.

### **2.3.1 Black Box Model**

A Black Box Model (BBM) is a visual representation of the inputs and outputs of energies, materials, and signals for the device as a whole. Figure 3 showcases the BBM for the Aero Micro team.



Figure 3: Black Box Model

This visual aid helps the team think about what needs to go into the device to ensure that it will meet its primary function. For this device the inputs of energy flow are electrical, rotational, and thrust, while the outputs are lift, thrust, thermal and rotational. The material inputs are airflow, and the outputs are drag, lift and airflow. The signal flows are the RC controllers and the ON/OFF switches, with the outputs the same.

#### **2.3.2 Functional Model**

A functional model is based off the BBM, it shows a detailed breakdown of how the inputs and outputs of the device flow through each other. Much like the BBM, the flows are outlined by the solid line being energy flow, the bolded line being material flow and the dotted line being the signal flow. Figure 4 shows the updated functional model for the Aero Micro team.



Figure 4: Functional Model

While creating the final design the team relied heavily on the functional model which helped create and analyze the Failure Mode Analysis in Section 4, enabling the team to focus on what failure modes are connected to each other. It also helped the team show how they needed to direct certain flows, such as energy and the control system. This led to the team creating a different structure, smaller fuselage with motor and servo pockets as well as having stronger batteries to make sure everything within the plane can get the power it needs.

# *2.4 House of Quality (HoQ)*

The House of Quality or the QFD (Appendix A), is a process of comparing the Customer Requirements and the Engineering Requirements and ranking how each one compares to each other. This enabled the team to decide which CRs and ERs were most important and therefore needed to be focused on the most, while also showcasing which ERs would meet the requirements of the CRs. The sections were ranked using the 1-3-9 rule. 1 being they affect each other the least, 3 being medium affect, and 9 being that they highly affect each other. If a cell is left empty, there is no correlation. As the team went into the concept design process, the QFD was analyzed showing that the top three main focus areas of the concept variants should be:

- 1. Meeting the SAE rules and regulations
- 2. Adequate servo size for aerodynamic forces
- 3. Thrust

While the first one is the general goal of the overall project, it ensured that the team would focus their energy on meeting the requirements. While two and three are more technical requirements that the team must keep in mind to ensure that the device will be able to take off and land properly. Looking at the QFD (Appendix A, Figure --) the top portion shows how the most important technical

requirements relate to each other, again using the 1-3-9 method. The right half is the customer opinion survey, which showcases how three related projects relate to the team's current project. While the bottom of the QFD shows how the technical requirements are measured and the target weights for each. The weights were decided by the team, taking into account the SAE Aero competition rules.

After the QFD was created, the team came together to decide how to test each of the Engineering requirements (ER) to prove for one, that they could be tested and measured and two, that the requirements could be met through the design that the team created. These testing procedures will be discussed further in Section 3.

## *2.5 Standards, Codes, and Regulations*

This section will provide a table of standards for specifications applicable to this project. Standards come from society, so we need to discuss why each standard is applicable to this project.

<b>Standard</b> Number or Code	<b>Title of Standard</b>	<b>How it applies to Project</b>
AGMA 943-	Tolerances for Spur and Helical	The latest standard document issued by AGMA
A22	Racks	, helpful for the application of gears in design.
<b>ANSI 105-</b>	Hand Protection Classification	It helps to reduce the probability of personal injury
2016		during the production process and protect the producer.
<b>ASME Y14.5-</b>	Dimensioning and Tolerancing	It is used to read and drawings, which can increase the accuracy of manufacturing and drawing.

Table 2: Standards of Practice as Applied to this Project



# **3 Testing Procedures (TPs)**

The testing procedures that will be used will determine the validity of a subsystem through various stresses and forces applied to each design as well as electronic setup and corrections. It will describe in detail what materials and equipment are needed for each test and how the team can acquire them. The testing procedures will be thorough so that each engineering requirement will be identified and tested and will then show how each requirement has been satisfied.

## *3.1 Testing Procedure 1: Wing Durability*

This will test the durability of various wing designs that were designed by each member of the team. Each design will undergo various stress and torque tests on the wing to find how much deflection will occur. This test will also account for strength to weight ratios as well.

#### **Satisfied engineering requirements:**

- Lightweight
- Increase durability
- Increase impact tolerance
- Optimize safety factor
- Wing span of 48 inches or less

#### **3.1.1 Testing Procedure 1: Objective**

The test will use three different types of forces applied to each wing. The first will be both ends of the wing secured with weight placed on the middle and will be measured by the displacement of the wing. This will test the wings strength at the middle where it will be attached to the plane. The second test will be one end of the wing secured while another end of the wing has weight placed on it and will be measured by displacement. This will be testing the strength of the wings at the ends. The third test will have one end of the wing secured and the other end of the wing having applied torque on it where it will be measured in displacement. This will determine the wings strength during flight and account for aerodynamic forces.

### **3.1.2 Testing Procedure 1: Resources Required**

All team members are required to do this test.

#### **Materials:**

- Torque wrench
- Balsa wood
- Hot glue
- Tape
- Foam
- Other miscellaneous materials made by members

### **3.1.3 Testing Procedure 1: Schedule**

This test will take several hours due to setup time to test wings. It will be run on each team member's individual time and at their current location.

# *3.2 Testing Procedure 2: Fuselage volume*

This test will determine if the fuselage is of adequate size for all electronic components and cargo bay. The fuselage will be manufactured and assembled for this test. The test will include fitting and sizing of components in the fuselage.

#### **Satisfied engineering requirements:**

- Meets SAE rules and regulations
- Payload unloading time
- Cargo bay

### **3.2.1 Testing Procedure 2: Objective**

The objective of this test is to find a proper size of fuselage for our plane. It is critical that the fuselage has enough room for the electronics and a cargo bay otherwise the team will run into regulation problems in the competition. The test will include assembling the fuselage and organizing the interior area to fit all electrical components completely and securely. It will also assess the area for the cargo bay and how weights will be placed.

### **3.2.2 Testing Procedure 2: Resources Required**

At least one team member is required to do this test. To assemble the fuselage basic hand tools are required to cut and manufacture individual parts.

#### **Materials:**

- Fuselage
- Battery
- ESC
- Servos
- Motor
- Receiver
- Cargo bay weights
- Adhesives

#### **3.2.3 Testing Procedure 2: Schedule**

This test will take several hours due to the meticulous work that is involved. The fuselage must be completely manufactured before this test can occur. This test should be run within the first weeks of the fall semester.

## *3.3 Testing Procedure 3: Electronics*

This test will confirm that all electronics within the plane are working properly, and movement of components is in the correct direction. Each servo and motor will be monitored by a team member and adjusted with the transmitter to correct it.

Satisfied engineering requirements:

- Increased reliability
- Power limiter
- Must have 4 battery cells or less
- Must use 4.3 GHz radio control system

### **3.3.1 Testing Procedure 3: Objective**

Successfully setup electronics including servos, motor, and transmitter-receiver communication. All electronics must communicate and work properly to provide a successful flight of the plane.

### **3.3.2 Testing Procedure 3: Resources Required**

All electronic components will be required for this test.

### **3.3.3 Testing Procedure 3: Schedule**

The test will take several hours to complete due to unforeseen errors in electronic setup and diagnosis of problems. It will take place when electronic components arrive (early August). Test will be done outside of school semester and therefore does not fit in semester schedule.

## *3.4 Testing Procedure 4: Fuselage to tail connection*

This test will be conducted by each teammate to construct a design for the structure connecting the tail and fuselage together. Each design will be weighted based on cost and strength to weight ratio as well as subjected to various stress tests.

Satisfied engineering requirements:

- Lightweight
- Increase durability
- Increase impact tolerance
- Optimize safety factor
- Cannot exceed 55 pounds
- Low cost

### **3.4.1 Testing Procedure 4: Objective**

The objective of this test is to determine a suitable structure and material to connect the tail and fuselage together. Each team member's design will be evaluated based on weight, cost, size, and strength. The test will measure deflection under load where one end of the structure is secured, and the other end is suspended. The second test will have the structure placed on the plane and measure deflection if

applicable.

### **3.4.2 Testing Procedure 4: Resources Required**

All team members are required to attend this test. Team-built structures are required to complete this test.

#### **Materials:**

- Adhesives (hot glue)
- Mounting points (nuts, bolts, rivets)

### **3.4.3 Testing Procedure 4: Schedule**

This test will be completed within the first weeks of the second semester. The time to complete the test will be several hours due to tedious work mounting structures to plane and perform stress tests.

# *3.5 Testing Procedure 5: Flight and Performance*

In this test we will take the fully assembled plane and fly it as well as observe its capabilities on the ground such as turning radius and rolling over rough terrain. It will also test the unloading time of the cargo. The team will test fly the plane and will observe the flight which will then lead to necessary changes and adjustments to the plane where applicable.

#### **Satisfied engineering requirements:**

- Increased reliability
- Increased durability
- Lift force
- Drag force
- Thrust
- Ground turning radius
- Payload unloading time
- Low control surface slop
- Adequate servo sizing for aerodynamic forces
- Landing within 200ft
- Takeoff within 8ft

### **3.5.1 Testing Procedure 5: Objective**

The test will take place on NAU campus at various locations such as one of the soccer or football fields. A team member will control the plane and begin to fly it. All team members will observe it in flight and the member controlling the plane will pay close attention as to how it is flying. This will test the real-world application of our design. It will assess the planes turning radius, ground stability, and payload unloading time as well.

#### **3.5.2 Testing Procedure 5: Resources Required**

All team members must be in attendance for this test. An open field is required to fly the plane. The fully assembled plane, transmitter, and a charged battery are required to complete this test.

### **3.5.3 Testing Procedure 5: Schedule**

This test should be completed at the end of the first month of next semester. The time to complete this test should be at least 3 hours due to recharging the battery, analyzing the plane during flight, and optimizing cargo bay unloading time.

# **4 Risk Analysis and Mitigation**

For this project the team created a Failure Mode and Effects Analysis (FMEA). This is used to outline potential failures within the subsystems of the device, what the effects of it may be and how the team will then take this information and mitigate these potential failures as they construct the final design. A full FMEA was created with 40 total potential failures for the whole system, what it could be caused by, the lasting effects, and how the failure could be mitigated. Discussed in the following section are the top ten potential critical failures, with their effects and mitigation strategies.

# *4.1 Critical Failures*

### **4.1.1 Potential Critical Failure 1: Aileron: Surface Fatigue**

Ailerons are located on the wings and tail of the plane. Surface fatigue on the aileron could be created by crash landings or just general use of the device, due to adjusting, take-off and landing. The effect of this failure is not only a poor appearance, but it also could create extra drag and could lead to full failure of the subsystem if it is not monitored. To mitigate this failure layering of hardened materials over the surface paired with constant physical inspection will be conducted.

### **4.1.2 Potential Critical Failure 2: Aileron: Low-cycle Fatigue**

The ailerons are controlled by servos, these servos in the wings create the lift and drag of the plane. Due to these forces, the ailerons are subject to low-cycle fatigue from raising up and down. This is caused by general use but can be elevated by crash landings. The effect of this failure is damage at main connection points and possible warping of the aileron itself. To mitigate this failure reinforced connection points could be made, along with proper lubrication.

### **4.1.3 Potential Critical Failure 3: Elevator: Abrasive Wear**

The elevator is also located on the wings and tail of the plane. They are subject to forces not only through the aileron, but also general wind forces. The abrasive wear on the elevators could be due to general use of adjusting, take-off and landing or a crash landing. The effect of this failure is poor appearance, potential loss of control, creation of drag and/or complete subsystem failure. To mitigate this failure the elevators would need a layered, reinforced outer shell.

### **4.1.4 Potential Critical Failure 4: Motor: High-cycle Fatigue**

The motor is the driving force of the plane, that being said the constant ON/OFF, throttling and holding of constant speeds and overloading creates high-cycle fatigue on the entire subsystem. The effects of these actions are loss of power, warping, smoke, and potential subsystem failure. To mitigate these effects, proper lubrication, proper power distribution and having a high torque motor would be used.

## **4.1.5 Potential Critical Failure 5: Servo: High-cycle Fatigue**

Much like the motors the servos are the driving points of the ailerons and the elevators, this leads to highcycle fatigue. The effects of this fatigue are noise, loss of power, smoke, and potential full subsystem failure. This can be mitigated by having proper lubrication, proper power distribution and having high torque, metal gear servos.

### **4.1.6 Potential Critical Failure 6: Aileron: Abrasive Wear**

Much like the surface fatigue of the aileron, and the abrasive wear of the elevators, abrasive wear is caused by general use and crash landings. The effects of this failure could be poor appearance, possible warping, create unnecessary drag, and potential connection point failure. These can be mitigated by proper outer shell material layering that creates a strong outer surface to resist wear.

## **4.1.7 Potential Critical Failure 7: Landing Gear: Impact Fatigue**

For this project the landing gear needs to withstand heavy forces, especially during landing. These forces could cause impact fatigue. This fatigue is characterized by deflection of the material, cracks, yielding

and potential subsystem failure. To mitigate these potential failures the landing gear needs to be made of strong and heavy material, while reinforcing the connection points to ensure that the plane will land safely.

### **4.1.8 Potential Critical Failure 8: Elevator: Impact Deformation**

With the amount of forces on the elevators and their construction, any impact deformation caused by a crash landing or an accident in transportation could lead directly to a complete subsystem failure. In order to attempt to mitigate this complete failure, each elevator needs to have reinforced internal and external structures, and reinforced connection points. However, it would benefit the team to have replacement parts made.

### **4.1.9 Potential Critical Failure 9: Motor: Impact Fatigue**

Impact fatigue of the motor could be caused by crash landings, particularly hard landings, and overloading. It could be characterized by noise, loss of power, and potential failure of the motor. In order to mitigate this failure, the motor will have to have physical inspections after a crash or hard landing. With a particular focus on the connecting wires, ensuring that the power output has not changed.

### **4.1.10 Potential Critical Failure 10: Servo: Impact Fatigue**

Impact fatigue of the servos could be caused by crash landings, and overloading. It could be characterized by noise, loss of power, and potential failure of the servos. In order to mitigate this failure, each servo will have to have physical inspections after a crash. With a particular focus on the connecting wires, ensuring that the power output has not changed and that the gears are not slipping.

# *4.2 Risks and Trade-offs Analysis*

After careful analysis of the potential failure modes, there are a few risks and trade-offs that have surfaced. Many of the potential failures could be mitigated by adding internal reinforcements or adding layers to the outer subsystem shell. The trade-off for these fixes not only adds more weight, but also adds to the building materials budget. However, there are some subsystems that need this more than others, so the team could potentially cut costs by only focusing on what is vital to the success of the plane. This, however, could cause an unexpected failure. There are still risks after that as well, especially when adding more layers to the ailerons and elevators could cause connection breaks, abrasive wear and added weight. While the weight of a few layers might not seem like much, when it is all added together it makes a difference. This was a main reason for the team changing the fuselage and outer structure. After analyzing the FMEA, the team has decided that the elevators will have more protective layers added to them to ensure that they are properly protected due to them being such critical subsystems. During the building process the subsystems will be fully evaluated to see if there is a portion that needs to be adjusted more than others and the risks connected with those adjustments will be evaluated.

# **5 DESIGN SELECTED – First Semester**

This part contains a comprehensive description of the team's design and an overview of the changes in the existing design compared to the previous design. This part will explain the changes and why we made them. In addition, this part will also specifically explain how we will put design into practice and give a plan on how to implement the design.

# *5.1 Design Description*

This section will describe our designs in a comprehensive way, and clarify the changes of these designs compared with the previous ones, as well as the reasons for these changes.

### **5.1.1 Improved Design**

As shown in the drawing, the existing design applies the following design: flat wing, large capacity fuselage and cargo tank, double blade propeller, and retractable landing gear. Compared with the previous design, this design has added many details and made modifications on the previous basis to meet the needs of customers and reduce the construction cost as much as possible.



Figure 5: Improved Design



Figure 6: Exploded view

#### **5.1.2 Engineering Calculations**

#### **Wings**

Lift coefficient needed

Cy=2Y/( $\rho$ V^2S)= 2\*55lbf/(1.225kg/m^3)(20m/s)^2(100in^2)  $=15.478$ Maximum Shear Stress  $\tau = F/A = 551b f/2.19i n^2 = 244.651 N/1.413*10^2 - 3 m^2$  $=173.155$  KPa

#### **Fuselage**

 Cargo Bay Volume L x W x  $H = V$  9 in∗4 in∗3.82 in=137.52 in^3 Impact Force F=  $(m*g*h)/d = (3.27 lb*384 m/s*5 in)/(.1 in) = 62,784 lb in/s$ 

### **Electronics**

Thrust Thrust = weight  $*$  thrust/weight ratio Thrust =  $1800g * 0.7 = 1260g$ Power = thrust  $*$  power/thrust ratio Power =  $1260 \text{ g} * 0.226 \text{ W/g} = 284.76 \text{ W}$ 

### **Landing gears**

Maximum force:  $F=M*a=3.9N$  Maximum deflection: ∆\_max= (FL^3)/48EI=0.0096m=0.96cm

#### **5.1.3 Reasons for the changes**

Base the preliminary report, after calculation and testing, we have found some unreasonable points of the previous design. First of all, we must ensure the reliability and applicability of the design, that is, we must meet the needs of customers. Secondly, the constructability of the design and the construction cost are also need to be considered. Through calculation and testing, we can remove some redundant designs, so as to save the use of materials and achieve a balance between reliability and cost. In addition, the testing and calculation work also provides a reliable assessment of the risks of the project, which enables us to find the risks in time and correct them. Therefore, modifying the design can also reduce the use and construction risks of the design. In conclusion, it has a lot of positive significance for the modification of the design.



Figure 7: Exploded view 2

## *5.2 Implementation Plan*

This section will describe how we will implement our design. This section will also clarify what resources we need to complete our work, including materials, grounds, personnel, etc. , as well as a schedule on how we will complete the work.

### **5.2.1 Resources needed**

As for the implementation of construction, we need many resources, including manpower, information, materials, and ground. In order to visually show the needs of these resources, we have made a Budget Analysis table and resource table. The tables can be seen in the appendix C and D.

#### **5.2.1 Schedule for next semester**

For the tasks of next semester, we can divide them into the following parts in detail: project determination, material preparation, product manufacturing, project adjustment, testing, and final report. in order to visually display the time periods applied to these tasks, we have made the following chart.



Figure 8: Next semester Schedule

# **6 CONCLUSIONS**

The SAE Aero Micro team has the responsibility of developing a remote-controlled aircraft that meets the rules and regulations of the SAE Aero competition. The main goal of the team is to create a plane that can take off and land successfully as well as have stable flight through the air. Critical requirements include a wingspan of 48 inches or less, it must be a safe design, and the entire system must be electric. This report took the black box model, functional model, customer requirements, engineering requirements, and house of quality from early in the semester to give an overview of what the projects requirements and functional breakdown is. It then covered the standards, codes, and regulations that apply to the project. It covered the testing procedures that outlined in detail the tests objectives, required resources, and schedule. Next, risk analysis and mitigation were used to determine each failure point in the plane. An analysis was done to mitigate these failure points and will then improve our design based on these findings. From these findings, the first semester design, outlined in section 5, was chosen. This section contained a comprehensive description of the team's design and an overview of the changes in the existing design compared to the previous design. It described in detail the changes that were made and why they were made and how the team will put the design into practice. The final solution proposed by the team is a flat wing design where the wing is located at the top of the fuselage. The fuselage will contain all electrical components which will be located under or near the wing to help with the center of gravity. Connecting the tail to the fuselage will be a lightweight structure made of rods that will keep the weight of the plane down and center of gravity at an appropriate location. The team decided to use a backwards tricycle landing gear which will help with tipping and landing/takeoff stability.

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# **8 APPENDICES**

## *8.1 Appendix A: House of Quality*



# *8.2 Appendix B: FMEA*



# *8.3 Appendix C: Budget Analysis*

As for the budget, the most important parts will be electronic equipment such as motors, servos, ECs, battery and charger, transmitters and receivers, which will account for nearly half of the budget. The

specific price is shown in the figures below.

Motor:

Avian 4250-800Ky Outrunner Brushless Motor

Spektrum - SPMXAM4700

\$89.99

Servos:

# A4040 MT/HS Micro Metal Gear HV Servo

Spektrum - SPMSA4040

\$54.99

Battery and charger:

## Smart G2 Powerstage Air Bundle: 3S 2200mAh LiPo Battery / S120 Charger

Spektrum - SPMXPSA200

Transmitter and receivers:

DX6e 6-Channel DSMX Transmitter with AR620

Spektrum - SPM6655

\$279.99

ECS:

Avian 60 Amp Brushless Smart ESC, 3S-6S (IC3)

Spektrum - SPMXAE1060

\$69.99

The ways of purchasing these equipment are as follows:

Motor:[https://www.horizonhobby.com/product/avian-4250-800kv-outrunner-brushless](https://www.horizonhobby.com/product/avian-4250-800kv-outrunner-brushless-motor/SPMXAM4700.html)[motor/SPMXAM4700.html](https://www.horizonhobby.com/product/avian-4250-800kv-outrunner-brushless-motor/SPMXAM4700.html)

Servos:[https://www.horizonhobby.com/product/a4040-mt-hs-micro-metal-gear-hv](https://www.horizonhobby.com/product/a4040-mt-hs-micro-metal-gear-hv-servo/SPMSA4040.html)[servo/SPMSA4040.html](https://www.horizonhobby.com/product/a4040-mt-hs-micro-metal-gear-hv-servo/SPMSA4040.html)

Transmitter and receiver:[https://www.horizonhobby.com/product/dx6e-6-channel-dsmx-transmitter](https://www.horizonhobby.com/product/dx6e-6-channel-dsmx-transmitter-with-ar620/SPM6655.html)[with-ar620/SPM6655.html](https://www.horizonhobby.com/product/dx6e-6-channel-dsmx-transmitter-with-ar620/SPM6655.html)

ESC:[https://www.horizonhobby.com/product/avian-60-amp-brushless-smart-esc-3s-6s](https://www.horizonhobby.com/product/avian-60-amp-brushless-smart-esc-3s-6s-ic3/SPMXAE1060.html)[ic3/SPMXAE1060.html](https://www.horizonhobby.com/product/avian-60-amp-brushless-smart-esc-3s-6s-ic3/SPMXAE1060.html)

Battery and charger:[https://www.horizonhobby.com/product/smart-g2-powerstage-air-bundle-3s-](https://www.horizonhobby.com/product/smart-g2-powerstage-air-bundle-3s-2200mah-lipo-battery-s120-charger/SPMXPSA200.html)[2200mah-lipo-battery-s120-charger/SPMXPSA200.html](https://www.horizonhobby.com/product/smart-g2-powerstage-air-bundle-3s-2200mah-lipo-battery-s120-charger/SPMXPSA200.html)

The advantage of purchasing from these ways is that we can save taxes and postage (these expenses are not a small amount in most ways), so as to achieve the purpose of saving budget. In addition, other materials will be purchased locally to save transportation costs. Free materials provided by individuals or factories will not be included in the total budget. The saved budget will be used to deal with emergencies, thereby reducing risks.

## *8.4 Appendix D: Resources Table*

