# Plasticity Modeling Team F6

#### By: Omar AlMutairi - Nawaf Alkhalaf - Mutairan Alhabashi - Abdullah AlMutairi

# **Project description**

- -Description of the project:
- Demonstrate plasticity modeling.
- Who is sponsoring the project?
- 1. The Mechanical Engineering Department.
- 2. Dr. Feigenbaum
- Why is it important?
- Graduate level design class.



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# Background

- Plastic limit.
- Desktop sized.
- Frictional force.
- Free springs considered.
- Graphs. Force vs. Displacement.

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# Benchmarking

- Elastic Spring.
- Block resist moving.
- Yield strength.
- Do not require a lot of strength.



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# **Design Requirements**

- 1. Easy to carry.
- 2. Easy to store.
- 3. Able to generate graphs.
- 4. Able to be seen by 20 students.
- 5. Works in an xy-plane.
- 6. System must be around 40 lbs.

7. Works in both tension and compression. 8 Have a friction coefficient to the surface. 9. Easy to add and remove springs on demand. 10. Durable.

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# **Customer Requirements**

- 1. Desktop sized system, small to store in an office.
- 2. Large to be seen in the classroom of 20 students.
- 3. System will control by user.
- 4. System must work in both tension and compression.

5. User can change the direction of force at any point during loading, within the xy-plane.

- 6. Surface must have a friction coefficient.
- 7. Generate Force vs Displacement graphs.
- 8. Module built.

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### **Engineering Requirements**

Engineering Requirements	Tolerance Values
Spring Expansions	1 feet
Elasticity	3 feet
Pushing/Pulling Force	10 N
Frictional Factors	1
Weight of system	18 Kg
Length of Sliding Area	1 m
Wireless Control distance	5 m
Weight of Sliding Box	2 Kg
X Y direction displacement	1 m
Durability	2 years
Reliability	Maximum to all the targeted values

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### **House of Quality**

Customer Requirement	Weight	Engineering Requirement	Compat Design	Weight of system	Frictional Factor	Motion/Force sensor	Length of Sliding Area	Wireless Control distance	X & Y Displacement.	Elasticity	Pushing/Pulling Force	Build Box - material?	Spring Expansions	Durability	Reliability	Weight of Sliding Box
1. Easy to be stored in an office	10		9	3				1				9			3	9
2. Visable from a distance	4		1					1		3		9				9
3. Desktop sized	8		9	3								3		3	3	3
4. Various types of spring	1						3	3	3				9			
5. Portable	9		3	9								3			3	3
6. Easy to carry	6		3	9				1				3			1	3
7. Generate different types of graphs	7					9				9	9				9	
8. Module built	3				3		9	9	9	3		1	9	9		1
9. x&y displacment	5					9	9	9	9	3	3		3			
10. Friction surface	2				9									3		
Absolute Technical Importance (ATI)			211	189	27	108	75	95	75	99	78	198	51	93	150	198
Relative Technical Importance (RTI)			1	3	12	5	10	7	10	6	9	2	11	8	4	2
Target ER values			25"x25"	40 lbs	any -1	1	1m	5m	1m	3ft	10N	4"x4"	1 ft	2 yrs	max	8 lbs

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# **Designs considered**

Here are the options of two designs that our client expected to see from us in ME486C





Design 2

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### **Cont. designs considered**

Those are the ideas that we came up with as a team:



# **Continue design considered**

List of the advantages and disadvantages for the 3 & 4 designs system.

#### Design 3:

#### Advantages

- 1. Force curve is available so force will monitor continually and it can vary eventually
- 2. Removable spring can make it easy to adjust and slide over the surface.
- 3. Spring elasticity will not affect the elasticity of material

#### Disadvantages

- 1. Force .vs. displacement curve will form by the system which makes the system slower
- 2. Will not be portable

#### Design 4:

#### Advantages

- 1. Displacement and force curves will monitor through the gauges.
- 2. Easy to understand the material behavior from the live gauge results.
- 3. Portable system

#### Disadvantages

 Interlink of force gauge and spring gauge to form the force vs. displacement is difficult. Nawaf Alkhalaf 10/4/17
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### Schedule

 $4^{th}$  of October –  $5^{th}$  of November

- Finish up Preliminary Report.
- Verify design selected.
- Analytic Analysis Team Memo
- Final Presentation and Report.

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### Schedule

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	Task Name	% Complete	s	м	Т	W	Т	F	s	s	М	Т	W	Т	F	s	s	м	Т	W	Т	F	s	s	М	Т	W	т	F	
1	Preliminary Presentation	100%												Pr	elim	inary	Pre	sent	ation											
2	Preliminary Report	90%												- Pi	elimi	nary	Rep	ort												
3	Peer Evaluation I	0%												*					Pe	er E	valu	ation	1							
4	Analytical Analyses I Team Memo	0%																					Ar	alyti	ر ادم	unaly	ses	ITea	am N	4
5	Final Proposal Presentation	0%																							*			Fir	al F	1
6	Final Proposal Report	0%																										, Fip	hal F	2
7	Peer Evaluation II	0%																										<u> </u>	Pe	4
8	Analytical Analyses II Team Memo	0%																												
9	Individual Analytical Analysis II	0%																												
10	Final CAD package and BOM	0%																												
11	Final Prototypes Summary	0%																												
12	Final Proposal Revision	0%																												
13	Peer Evaluation III	0%																												

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# Budgeting

- Team proposed budget.
- Based on the final design chosen by the client.
- Range between \$500 \$2000.

Materials used in the design	Approximation costs						
Plastic box	50\$-150\$						
Arduino	27.95\$-350\$						
Sensors (BMP180) &(LM393)	6.99\$-35.99\$ & 5.34	\$-22.90\$					
Springs	3.60\$-12.07\$	Abdullah AlMutairi 10/4/17					

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### References

https://nau.edu/cefns/engineering/mechanical/faculty-staff/directory/heidi-feigenbaum/ [Accessed 4 Oct. 2017].

Anon, (2017). [online] Available at: http://R. Hill, Mathematical Theory of Plasticity, Oxford University Press, 1950. [Accessed 4 Oct. 2017].

### Questions

Thanks for listening