## Team 18F06 SumoBot Final CAD package and BOM

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Rashed Alfadhli

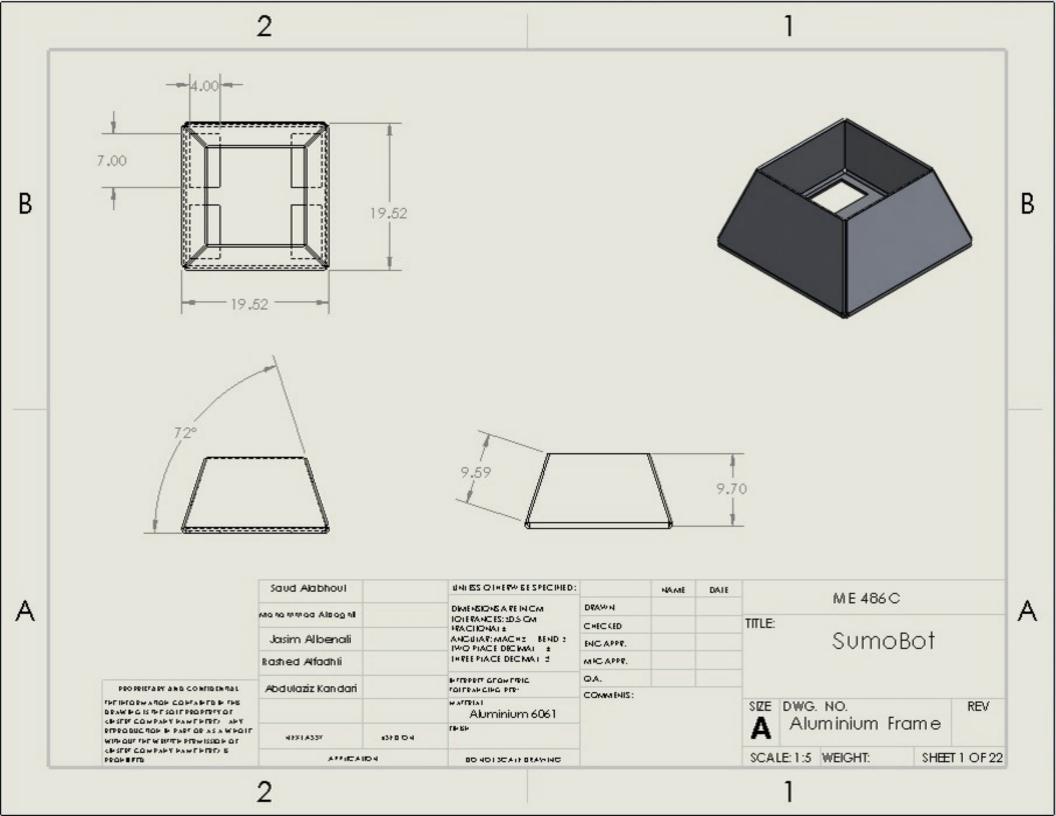
Abdulaziz Kandari

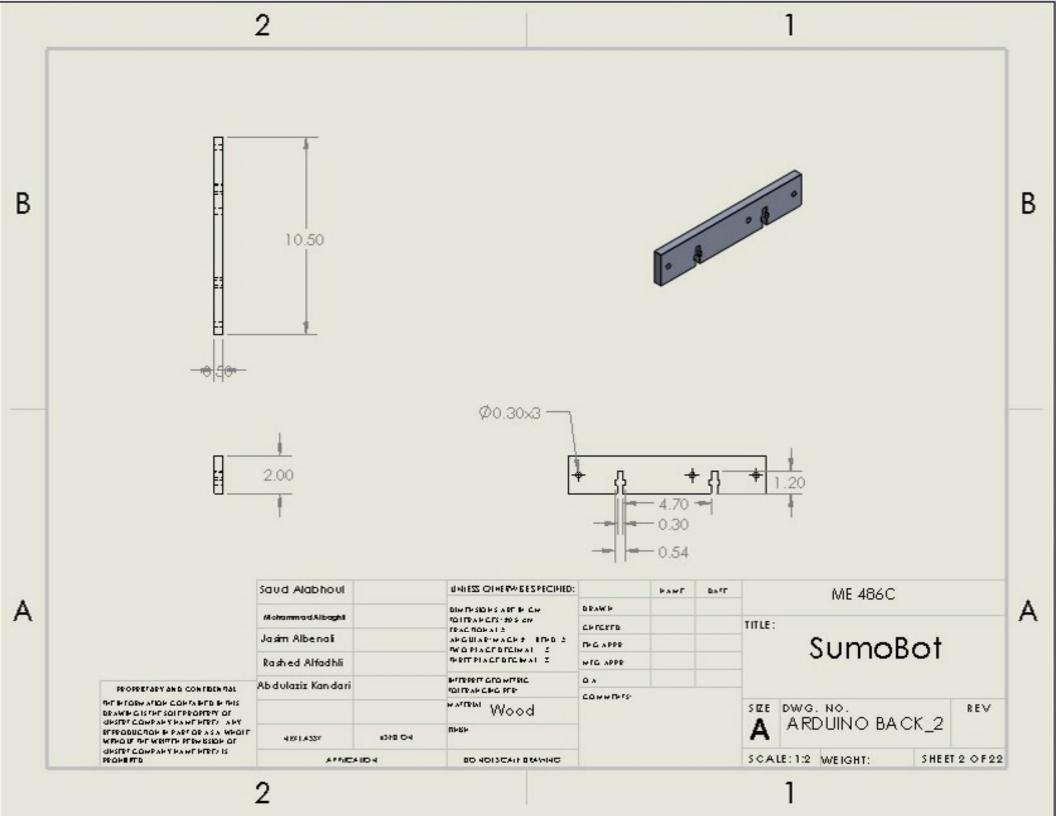
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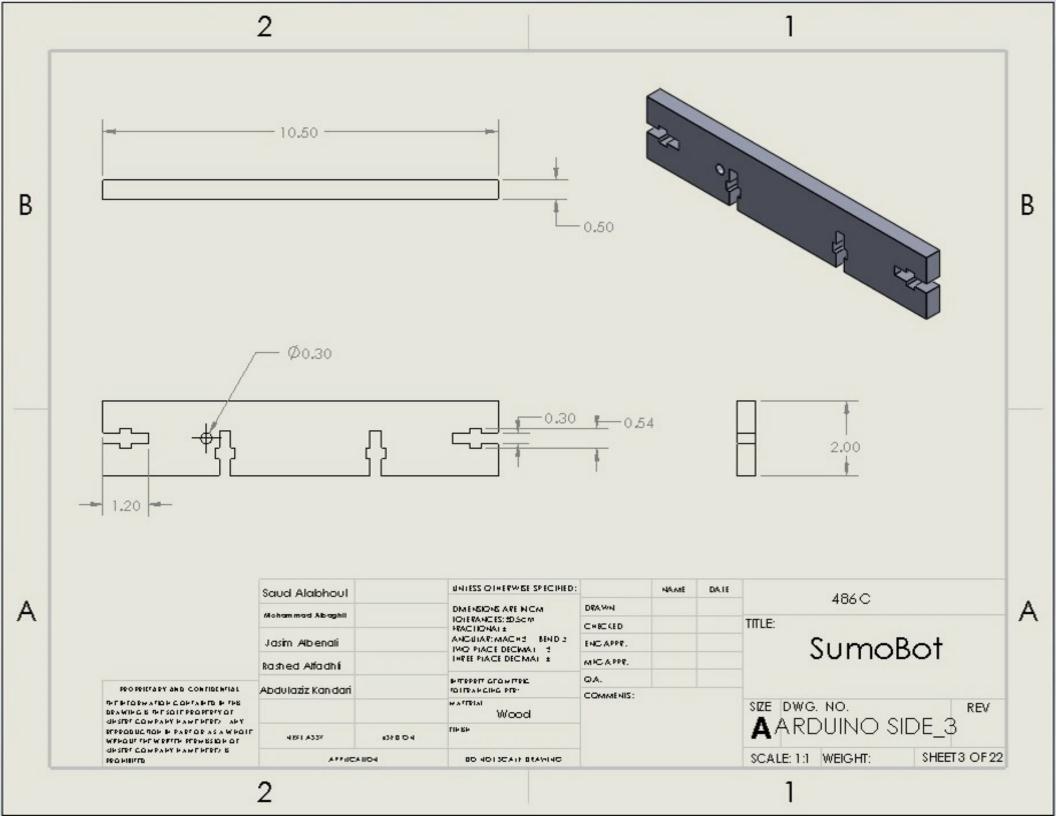


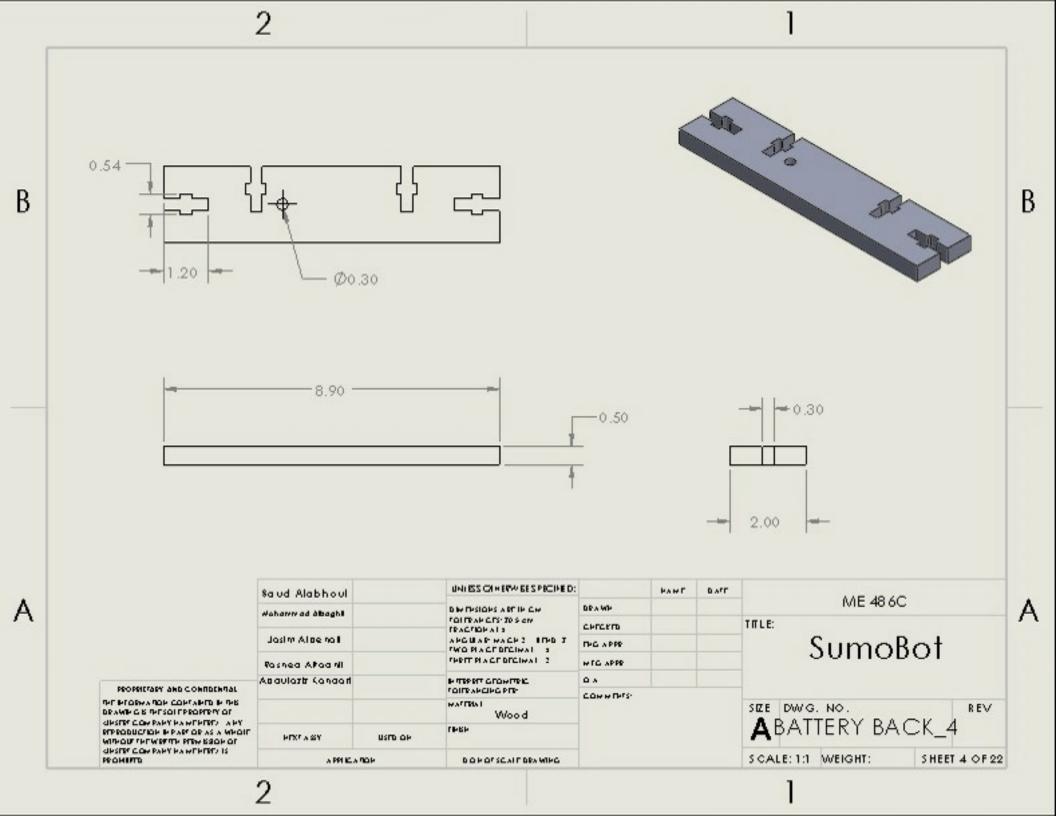
**Project Sponsor: Northern Arizona University** 

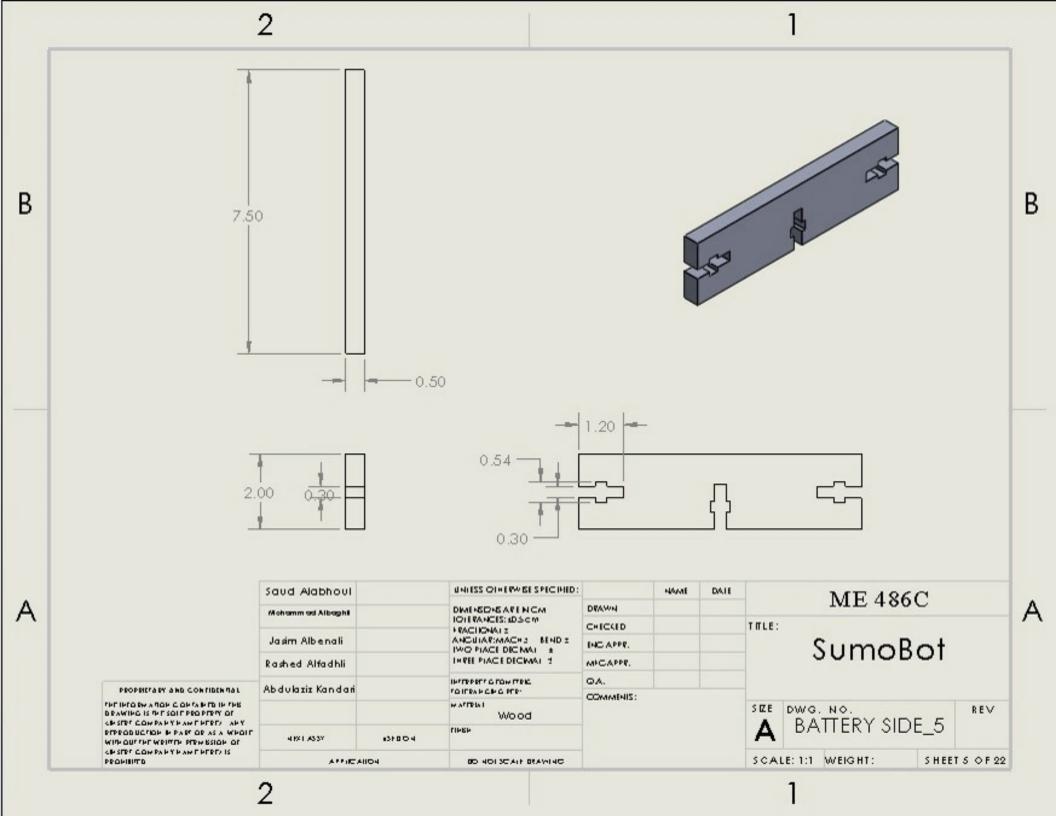
Faculty Advisor: Dr. Sarah Oman

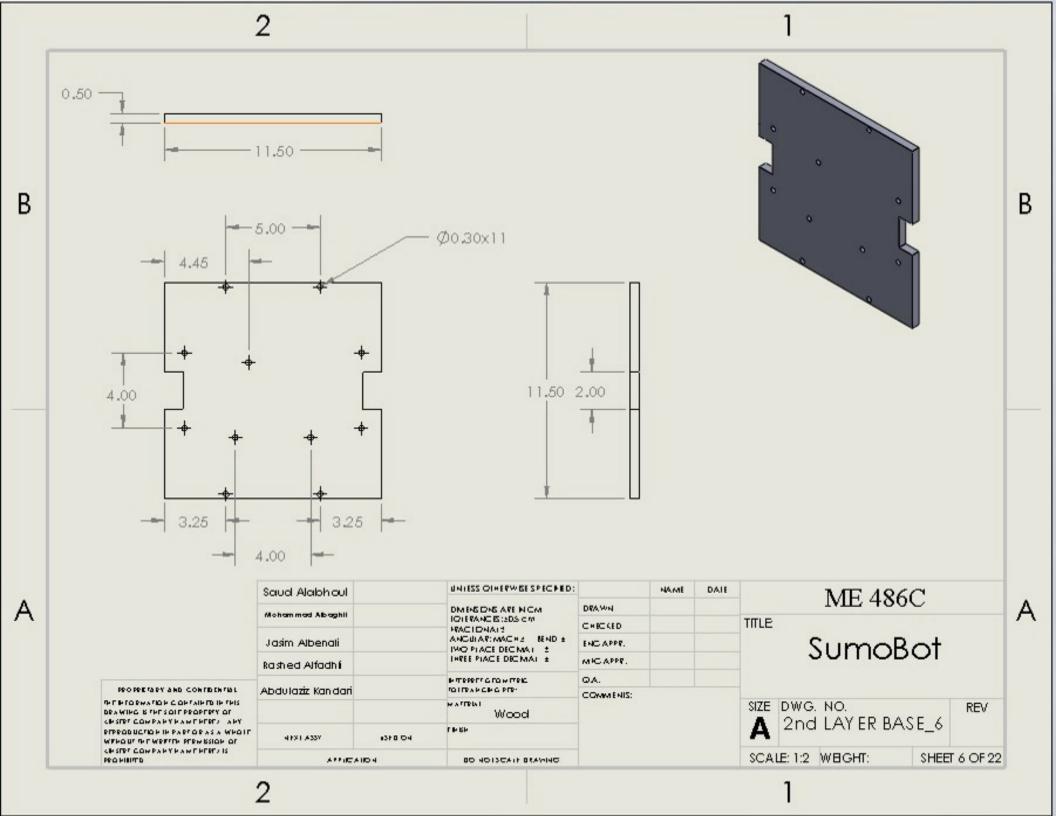


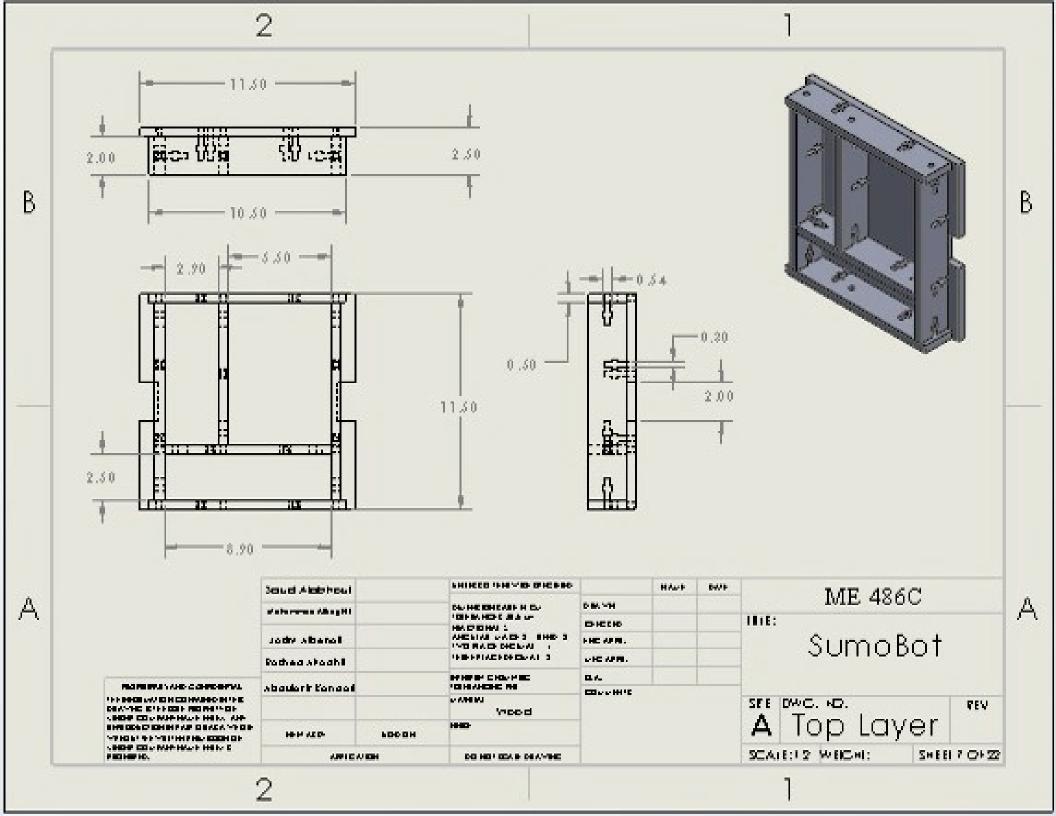


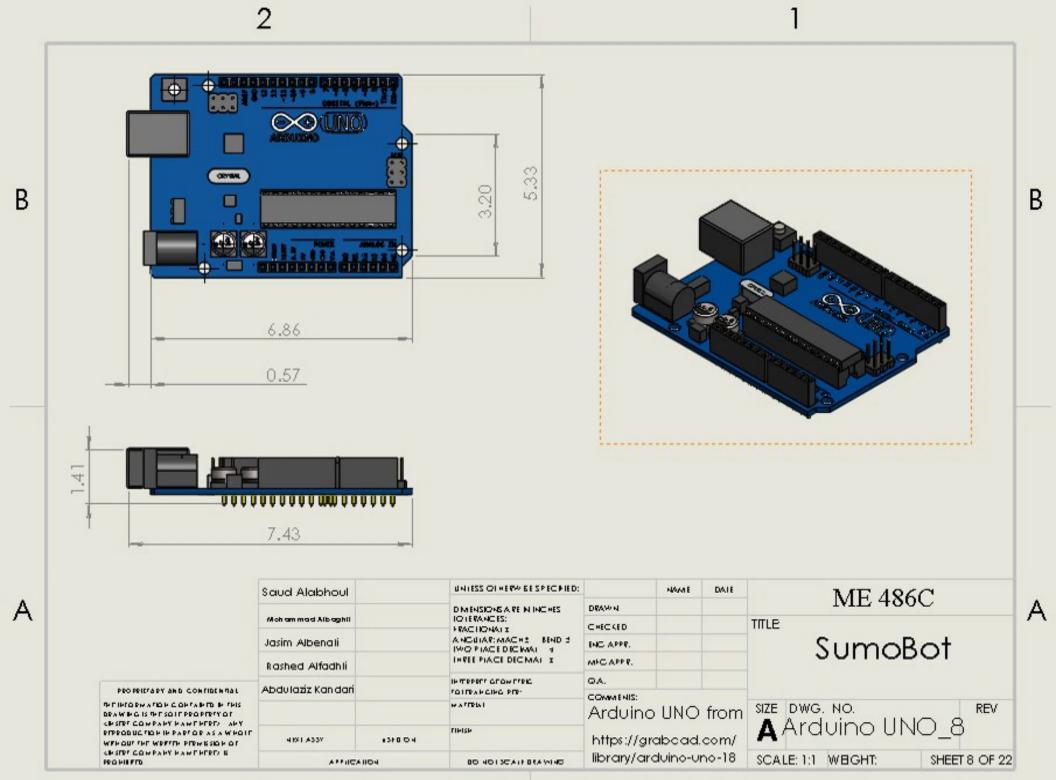






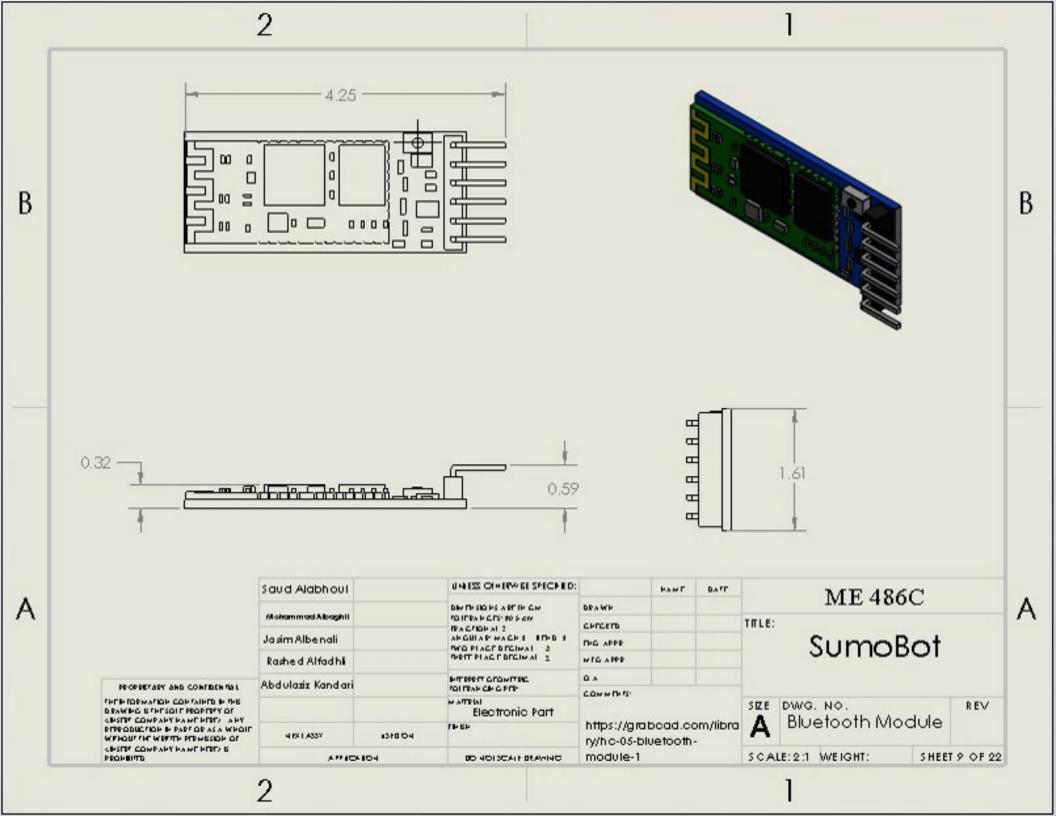


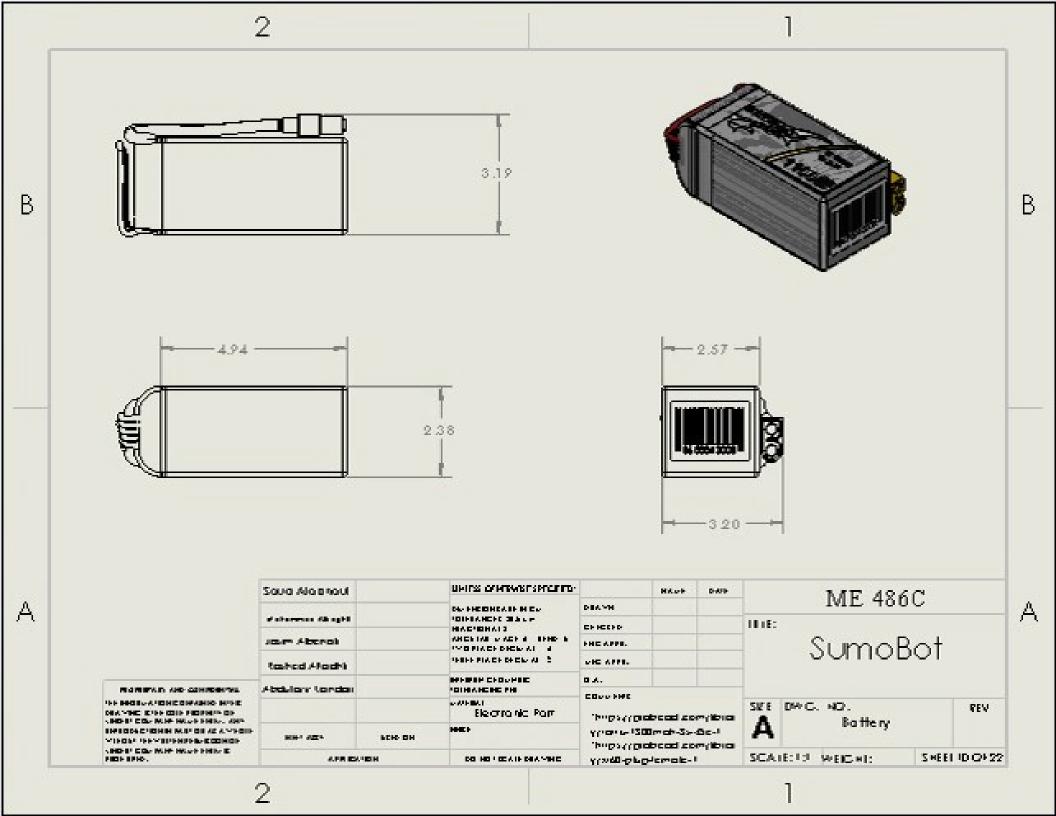


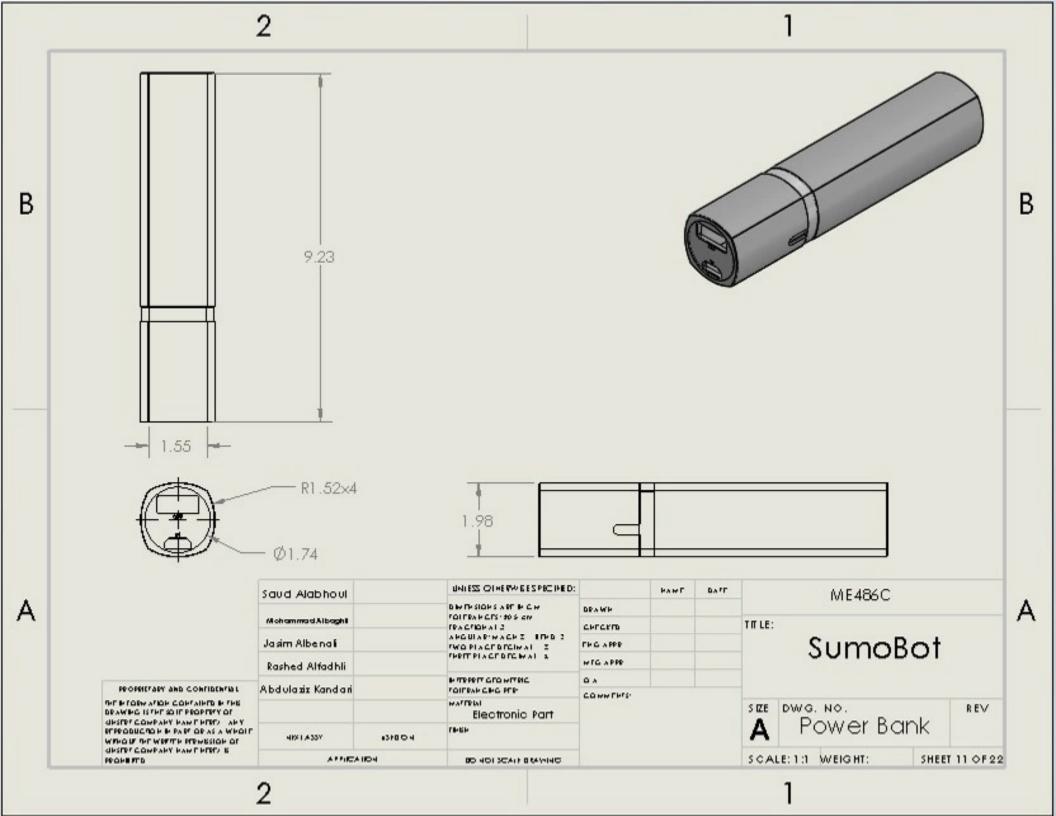


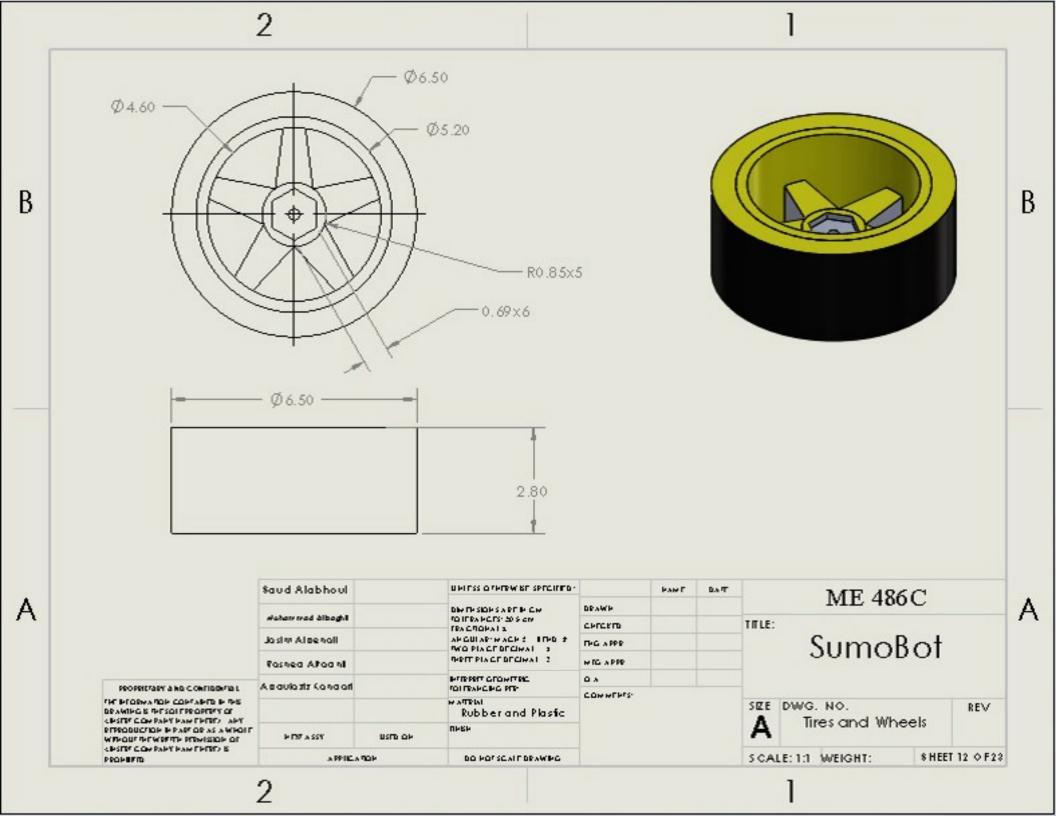
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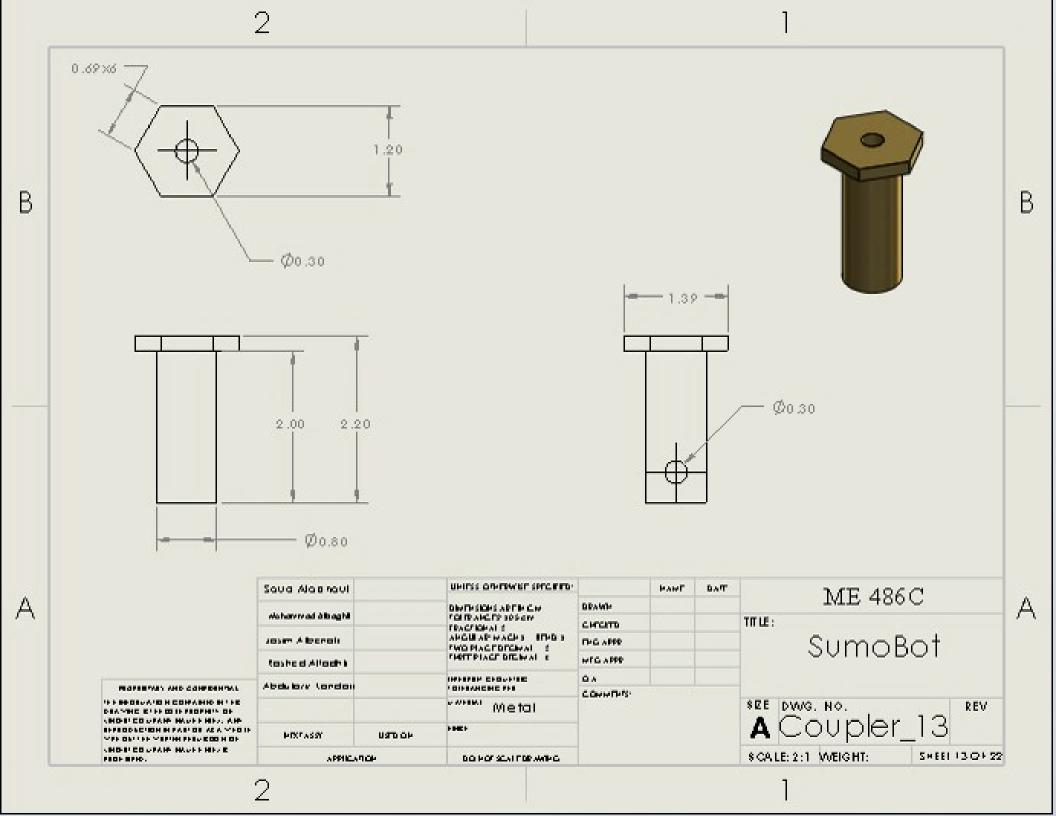
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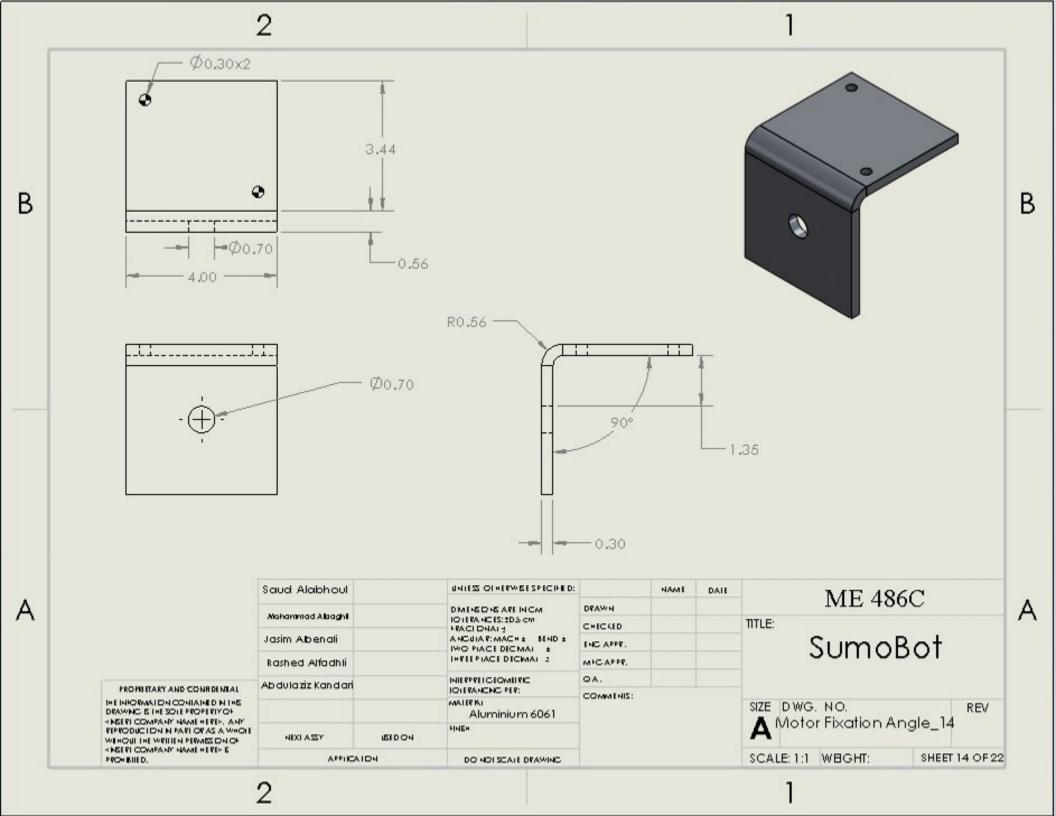


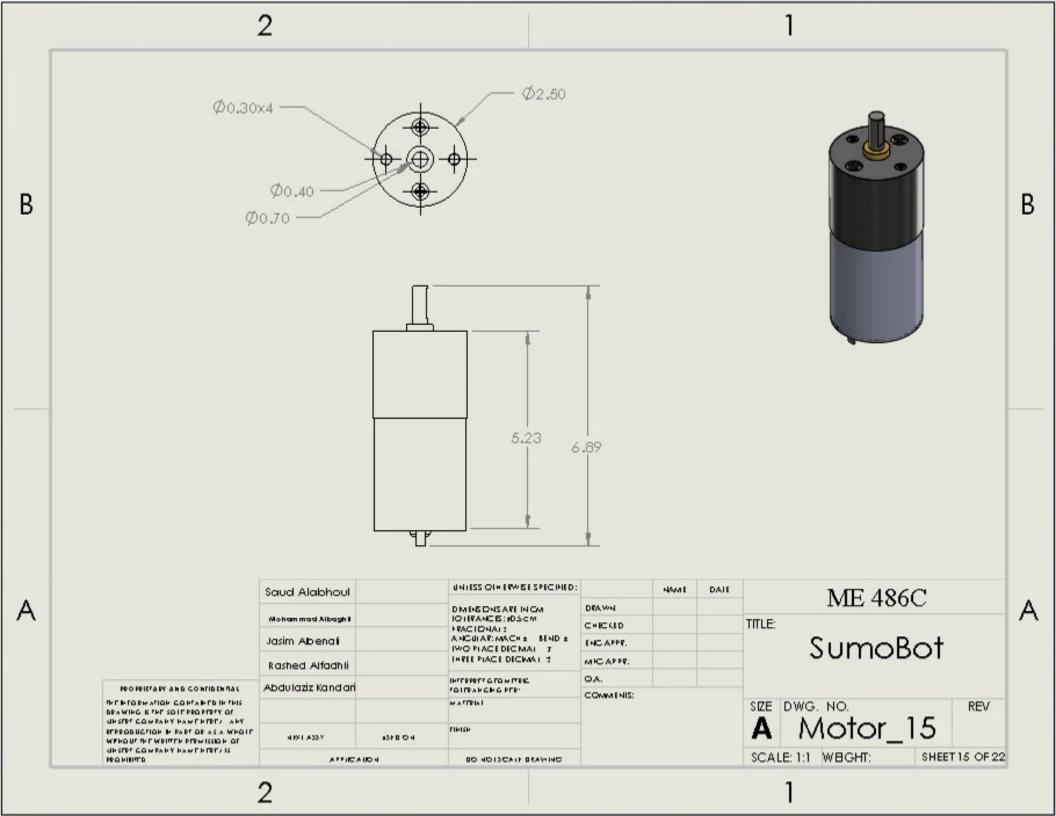


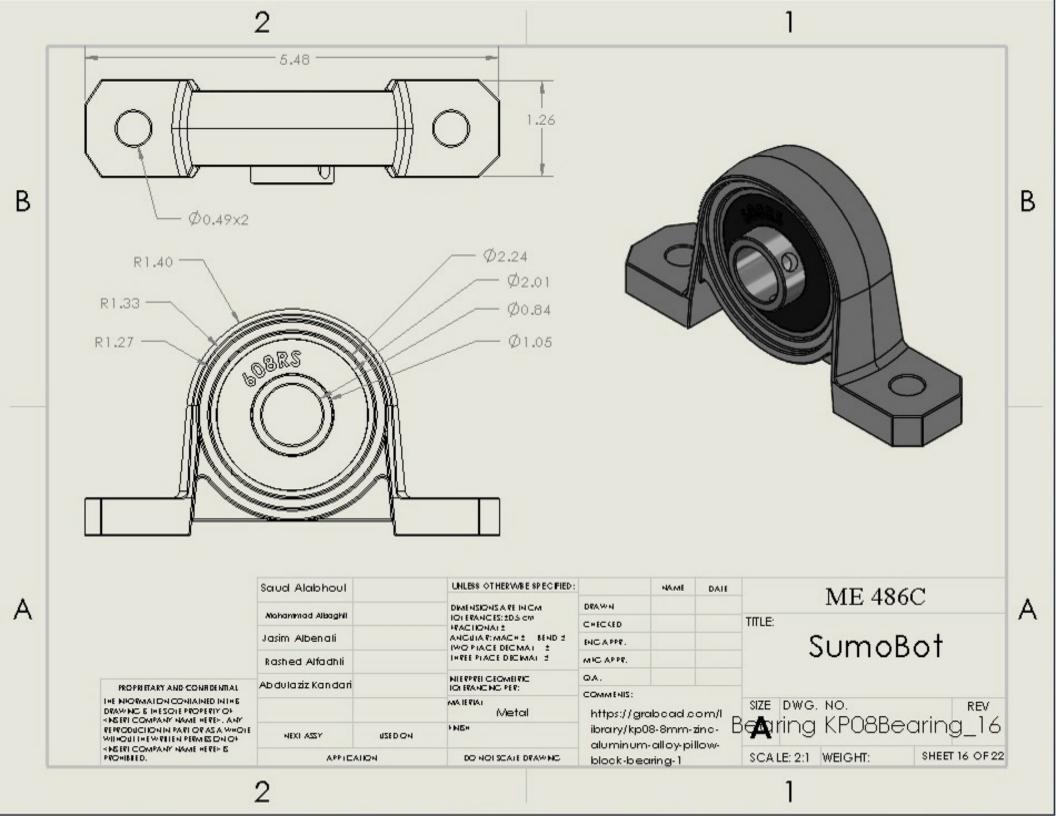


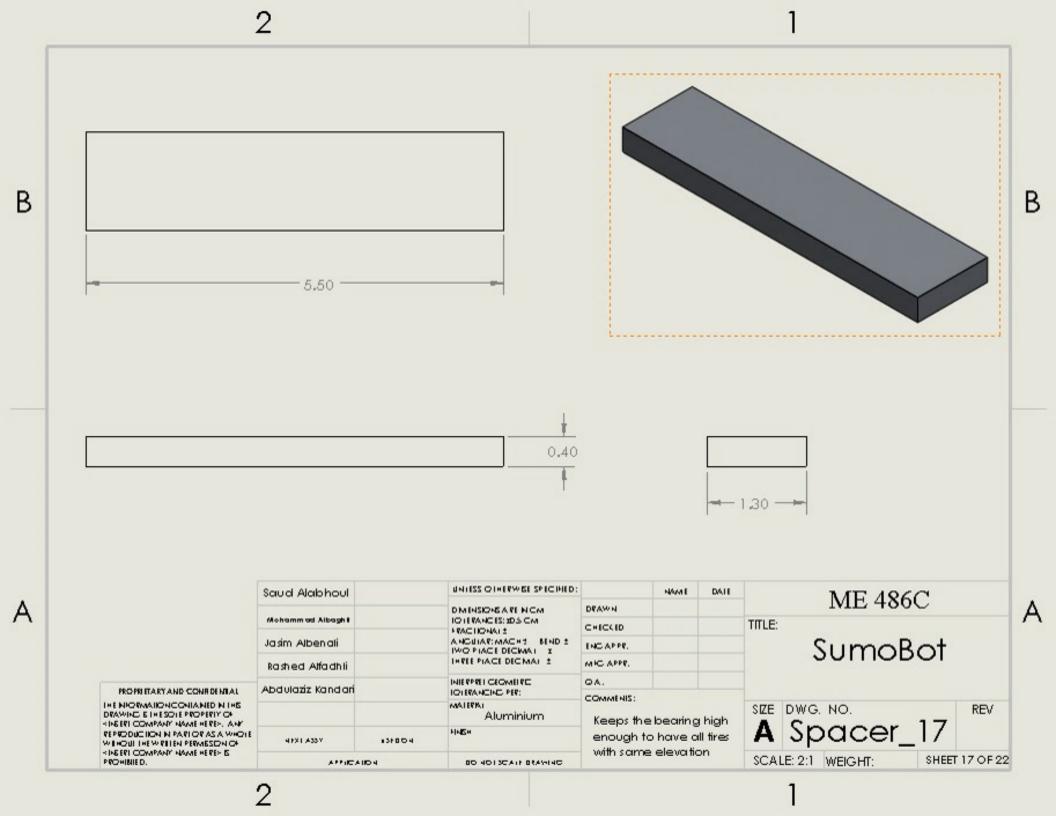


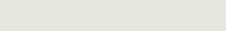






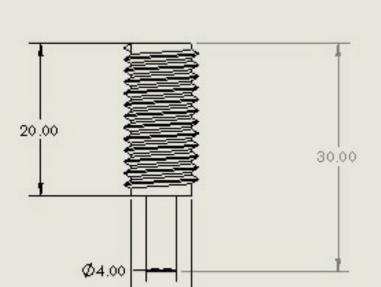






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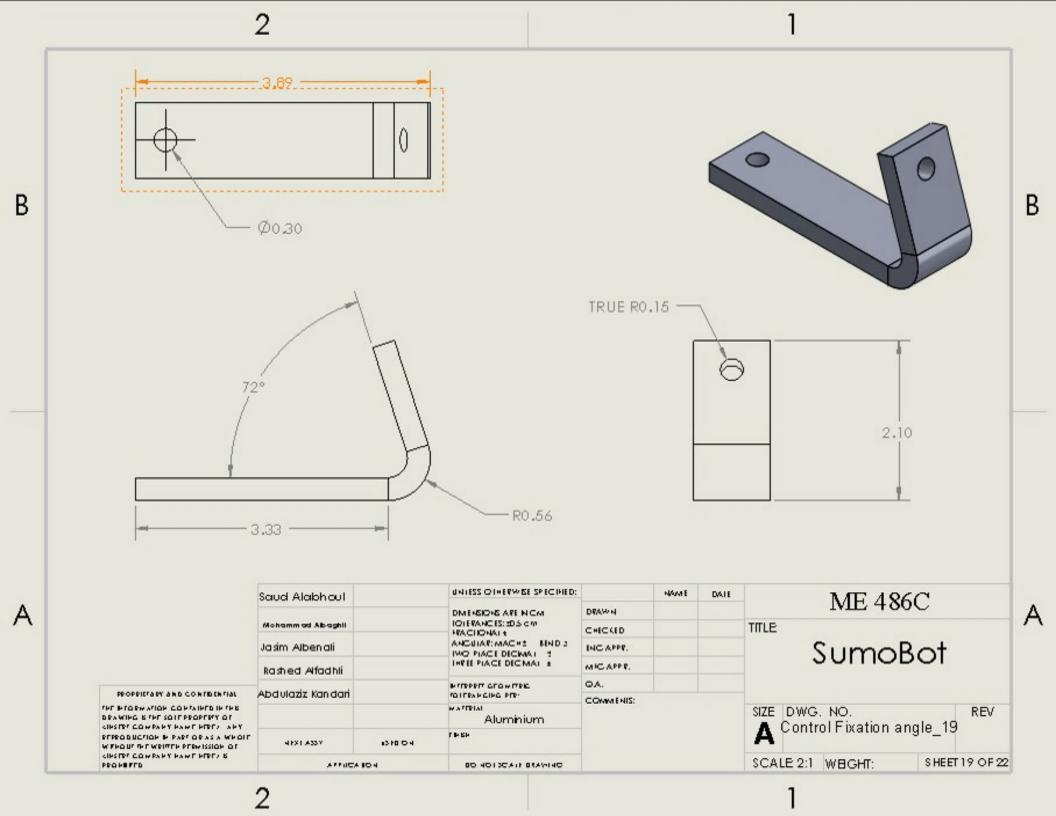
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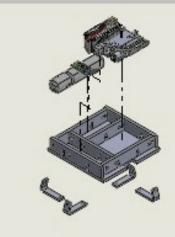
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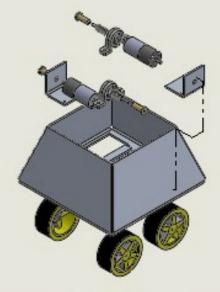
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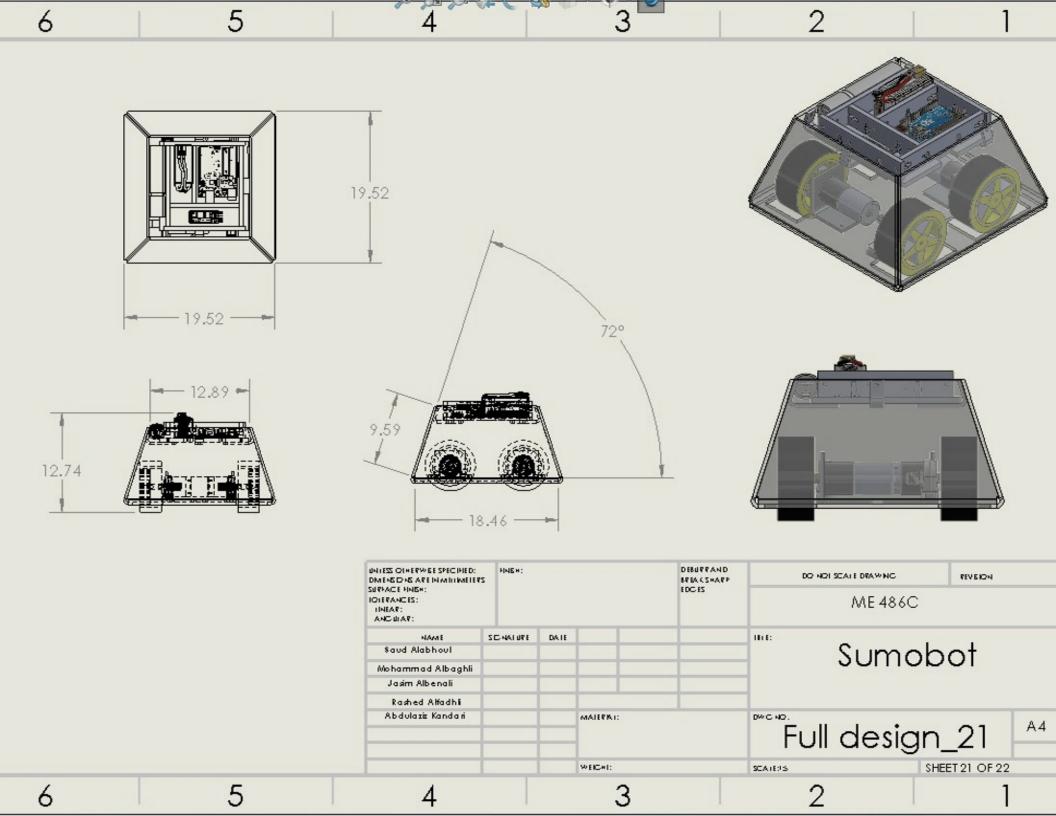
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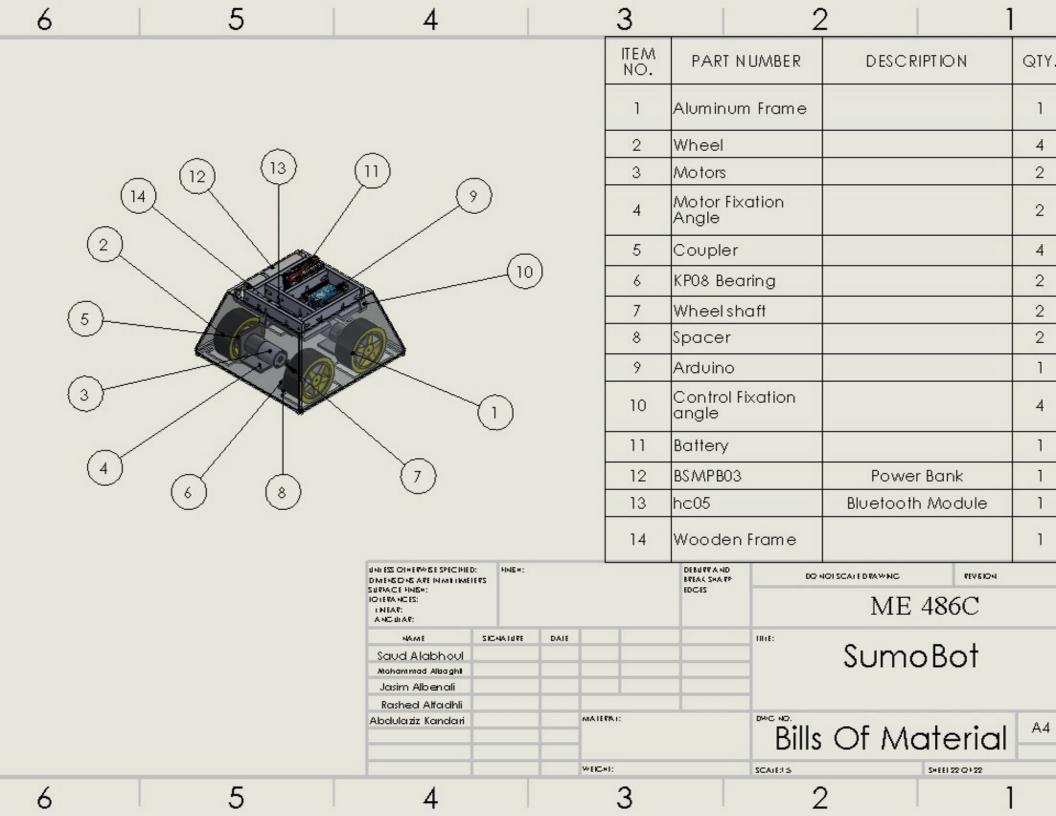
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## **Bill of Material**

Table 1: shows all the parts that is installed to get the full design without the extra parts.

Part No.	Part Name	Qty.	Description
1	Arduino UNO	1	Microcontroller
2	Battery	1	LIPO battery 1100 mAh
3	Motor	2	Motor 250 rpm and 8.8 kg/cm torque
4	Wheel	4	Rubber Wheel
5	Driver	1	Monster motor shield VNH2SP30
6	Bluetooth Module	1	HC05 Bluetooth Module
7	Aluminum Body	1	Metal Body
8	Power Bank	1	2000 mAh power bank
9	Block bearing	2	KP08 housing pillow block bearing
10	Wooden Frame	1	Controlling electronic parts on top of the device
11	Coupler	4	Connect the tires to the bearings and motors.
12	Motor fixation	2	Holds the motors in place.
13	Control Fixation	4	Holds the wooden frame in place.
14	Shaft	2	Shafts are connected from the bearing to the tires through the couplers.
15	Spacers	2	A spacer beneath each bearing to hold in place and to keep it high enough.