

Sumo Robotics

Team Members:

Saud Alabhoul, Jasim Albenali, Mohammad Albaghli, Abdulaziz Kandari Rashid Alfadhli

Description: Sumorobot 3kg (R/C)

Two Sumorobots challenge in a head-to-head match. With following the rules of sumo matches

Class	Height	Width	Length	Weigh
Mega Sumo - R/C	unlimited	20.0 cm	20.0 cm	3,000 g

Table 1: Measurements

Specification:-

- R/C Controlled Sumo robot
- Qualified of following the competition “Rules”
- Following (Width/Length/Weigh) limitations

Sponsorship of the project & Client

-Our Sponsor of the Sumorobot competition will be Northern Arizona University.

-Team 18F06 will prove to accomplish all necessary requirement of the sumo bot competition as undergraduates of ME students.

-The client will be the ROBOGAMES Competition.



Figure 1: NAU Logo



Figure 2: ROBOGAMES Logo

Newest Generation Sumobot “SandFlea” created by Boston dynamics

Specifications:-

- Battery & Propane powerd
- Weigh: 5kg, Height: 15cm, Joints: 5

Capabilities:-

- Jumps 10m
- 25 Bounces per charge

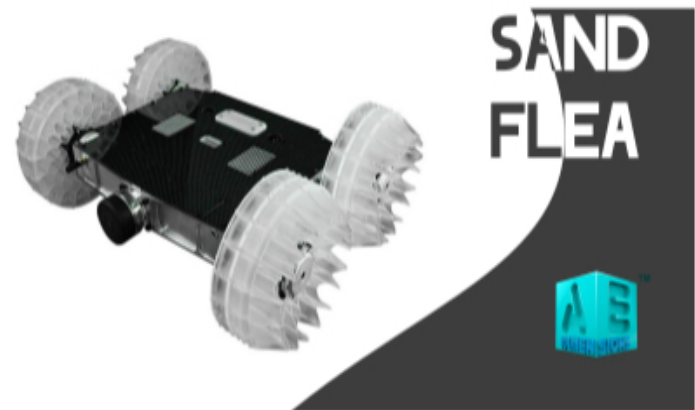


Figure 3: Sand Flea

Other similar low-budget sumobot

- *Low-cost 90\$*
- *Bluetooth controlled Sumobot*
- *Competition ready*



Figure 4: Android sumobot

Design Requirements

- a. Short charging time with long battery life.
 - Lasts 3 rounds each round is 3 minutes.
- b. R/C robot that does not have sticky substances
- c. Artbot prepared and Creative Design.
- d. No hazardous & dangerous material
- e. The controller does not exceed 75Mhz.

Customer Requirements

1. R/C Robot	Weight
I. Weigh	5
II. Durability	3
III. Portable	4
IV. Simplicity	2.5
V. Pausing Capabilities	3
VII. RC Controlled	5
VIII. Safety	4

Table 2:- Measurements

Engineering Requirements.

• Engineering Requirements
• Maintenance
• Remote Controlled
• Autonomous
• Torque
• Consistency
• Cost
• Minimizing Weight
Size
Power Source
Motor

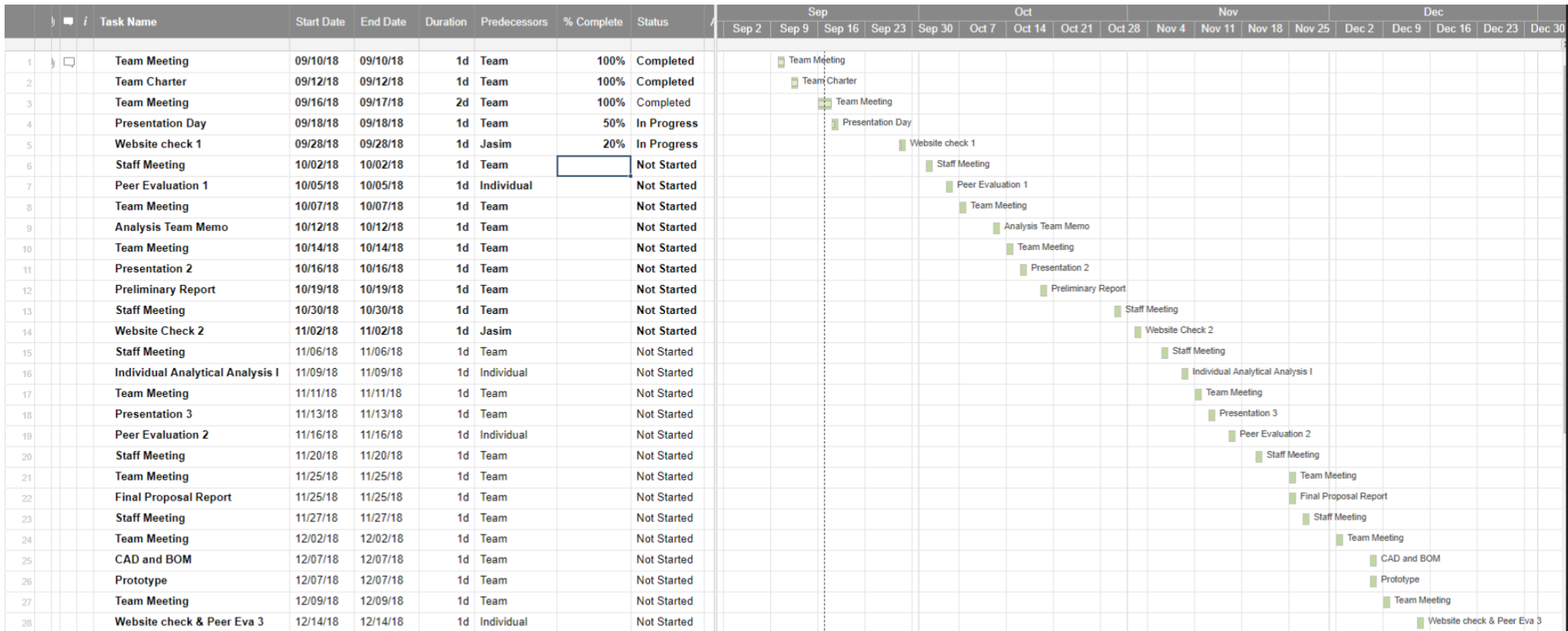
Table 4: ENG Requirements.

House of Quality

1	House of Quality (HoQ)												
2													
3	Customer Requirement	Weight	Engineering Requirement	Maintanance	Remote Controlled	Autonomous	Torque	Constancy	Cost	Minimizing Weigh	size	Power Source	Motor
4	Weigh	5		1	3	9		3		9	9	3	9
5	Durability	3		9	3		9	9	3	3	1	3	9
6	Portable	4		9	1			1	3	9	3	3	3
7	Simplicity	2.5		9	3	3	3	1	3	3	9	9	3
8	Pausing Capabilities	3		3	9	1		3		3		3	9
9	RC Controlled	5		9	9	3	3	3	9	1		3	9
10	Safety	4		3		3	1	1	3	1	1	9	9
11	Absolute Technical Importance (ATI)			156.5	107.5	82.5	54	76.5	85.5	115.5	86.5	103.5	199.5
12	Relative Technical Importance (RTI)			2	4	8	10	9	7	3	6	5	1
13	target unit of measurment			no unit	frequer	no unit	N*m	no unit	USD	g	cm	Watt	TBD
14	Target ER values			N/A	N/A	TBD	TBD	N/A	1000	3000	20*20	TBD	TBD
15	Tolerances of Ers			N/A	N/A	N/A	± 0.1		<100	<3000	<20*2	± 0.2	TBD

Table 4: HoQ.

Gantt Chart



Budget

- No Specific Budget
- Ranges between 1000~2000
- Recycling many parts of previous projects



Figure 5: Budget Plan

Questions?

References

- <https://www.instructables.com/id/Android-Controlled-Bluetooth-Sumobot-Ultimate-DIY-/>
- <http://blog.aedimensions.com/sand-flea-the-jumping-robot/>
- <https://www.bostondynamics.com/sandflea>
- <http://robogames.net/index.php>